

Closure Schemes for Nonlinear Bistable Systems Subjected to Correlated Noise: Applications to Energy Harvesting from Water Waves

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The moment equation closure minimization (MECM) method has been developed for the inexpensive approximation of the steady-state statistical structure of bistable systems, which have bimodal potential shapes and which are subjected to correlated excitation. Our approach relies on the derivation of moment equations that describe the dynamics governing the two-time statistics. These are then combined with a closure scheme that arises from a non-Gaussian probability density function (PDF) representation for the joint response-excitation statistics. We demonstrate its effectiveness through the application on a bistable nonlinear single-degree-of-freedom (SDOF) ocean wave energy harvester with linear damping, and the results compare favorably with direct Monte Carlo simulations.

INTRODUCTION

In numerous systems in engineering, uncertainty in the dynamics is as important as the known conservation laws. Such an uncertainty can be introduced by external stochastic excitations, e.g., energy harvesters or structural systems subjected to ocean waves, wind excitations, earthquakes, and impact loads (Grigoriu, 2002; Stratonovich, 1967; Sobczyk, 2001; Soong and Grigoriu, 1993; Naess and Moan, 2012; To, 2011). For these cases, deterministic models cannot capture or even describe the essential features of the response; to this end, understanding of the system dynamics and optimization of its parameters for the desired performance is a challenging task. On the other hand, a probabilistic perspective can, in principle, provide such information, but then the challenge is the numerical treatment of the resulting descriptive equations, which can be associated with prohibitive computational cost.

The focal point of this work is the development of computational methods for the inexpensive probabilistic description of nonlinear vibrational systems of low to moderate dimensionality subjected to correlated excitations. Depending on the system dimensionality and its dynamical characteristics, numerous techniques have been developed to quantify the response statistics, i.e., the probability density function (PDF) for the system state. For systems subjected to white noise, the Fokker–Planck equation provides a complete statistical description of the response statistics (Wojtkiewicz et al., 1999; Dunne and Ghanbari, 1997; Di Paola and Sofi, 2002). On the other hand, for systems subjected to correlated excitations, the joint response-excitation method provides a computational framework for the full statistical solution (Sapsis and Athanassoulis, 2008; Venturi et al., 2012; Cho et al., 2013). However, such methodologies rely on the solution of transport equations for the PDF, and they are associated with very high computational cost, especially when it comes to the optimization of system parameters.

To avoid the solution of transport equations for the PDF, semi-analytical approximative approaches have been developed that

significantly reduce the computational cost. Among them, the most popular in the context of structural systems is the statistical linearization method (Caughey, 1959; Caughey, 1963; Kazakov, 1954; Roberts and Spanos, 2003; Socha, 2008), which can also handle correlated excitations. The basic concept of this approach is to replace the original nonlinear equation of motion with a linear equation, which can be treated analytically, by minimizing the statistical difference between those two equations. Statistical linearization performs very well for systems with unimodal statistics, i.e., close to Gaussian. However, when the response is essentially nonlinear (e.g., as is the case for a double-well oscillator), the application of statistical linearization is less straightforward and involves the ad hoc selection of shape parameters for the response statistics (Crandall et al., 2005).

An alternative class of methods relies on the derivation of moment equations, describing the evolution of the joint response-excitation statistical moments or (depending on the nature of the stochastic excitation) the response statistical moments (Sancho, 1970; Bover, 1978; Beran, 1994). The challenge with moment equations arises if the system equation contains nonlinear terms, in which case we have the well-known closure problem. This requires the adoption of closure schemes or methods, which essentially truncate the infinite system of moment equations to a finite one. The simplest approach along these lines is the Gaussian closure (Iyengar and Dash, 1978), but nonlinear closure schemes have also been developed (Crandall, 1980; Crandall, 1985; Liu and Davies, 1988; Wu and Lin, 1984; Ibrahim et al., 1985; Grigoriu, 1991; Hasofer and Grigoriu, 1995; Wojtkiewicz et al., 1996; Grigoriu, 1999). In most cases these nonlinear approaches may offer some improvement compared with the stochastic linearization approach applied to nonlinear systems, but the associated computational cost is considerably larger (Noori et al., 1987). For strongly nonlinear systems, such as bistable systems, these improvements can be very small. The latter have become very popular in energy harvesting applications (Green et al., 2012; Harne and Wang, 2013; Daqaq, 2011; Halvorsen, 2013; Green et al., 2013; He and Daqaq, 2014; Mann and Sims, 2009; Barton et al., 2010), where there is a need for fast and reliable calculations that will be able to resolve the underlying nonlinear dynamics in order to provide optimal parameters of operation (Joo and Sapsis, 2014; Kluger et al., 2015).

The goal of this work is the development of a closure methodology that can overcome the limitations of traditional closure schemes

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and can approximate the steady-state statistical structure of bistable systems excited by correlated noise. We first formulate the moment equations for the joint PDF of the response and the excitation at two arbitrary time instants (Athanasoulis et al., 2013). To close the resulting system of moment equations, we formulate a two-time representation of the joint response-excitation PDF. We chose the representation so that the single-time statistics are consistent in form with the Fokker–Planck solution in steady state, while the correlation between two different time instants is assumed to have a Gaussian structure. Based on these two ingredients (dynamical information expressed as moment equations and assumed form of the response statistics), we formulate a minimization problem with respect to the unknown parameters of the PDF representation so that both the moment equations and the closure induced by the representation are optimally satisfied. For the case of unimodal systems, the described approach reproduces the statistical linearization method, whereas for bimodal systems it still provides meaningful and accurate results with very low computational cost.

The approach we developed allows for the inexpensive and accurate approximation of the second-order statistics of the system even for oscillators associated with double-well potentials. In addition, it allows for the semianalytical approximation of the full non-Gaussian joint response-excitation PDF in a postprocessing manner. We illustrate the approach we developed through a nonlinear single-degree-of-freedom (SDOF) ocean wave energy harvester with double-well potential subjected to correlated noise of the Pierson–Moskowitz power spectral density. We demonstrate how the proposed probabilistic framework can be used for performance optimization and the selection of parameters.

METHOD DESCRIPTION

In this section, we give a detailed description of the proposed method for the inexpensive computation of the response statistics for dynamical systems subjected to colored noise excitation. The computational approach relies on the following two basic ingredients:

- *Two-time statistical moment equations.* These equations will be derived directly from the system equation and will express the dynamics that govern the two-time statistics. For systems excited by white noise, single-time statistics are sufficient to describe the response, but for correlated excitation, this is not the case, and it is essential to consider higher-order moments. Note that higher-order (i.e., higher than two) statistical moment equations may be used, but in the context of this work, two-time statistics would be sufficient.

- *PDF representation for the joint response-excitation statistics.* This will be a family of PDFs that will express geometrical properties of the solution such as multimodality, tail decay properties, correlation structure between response and excitation, or others. In this work we will use representations inspired by the analytical solutions of the dynamical system when it is excited by white noise. These representations will reflect features of the Hamiltonian structure of the system and will be used to derive appropriate closure schemes that will be combined in the moment equations.

Based on these two ingredients, we will formulate a minimization problem with respect to the unknown parameters of the PDF representation so that both the moment equations and the closure induced by the proposed representation are optimally satisfied. We will see that for the case of unimodal systems, the described approach reproduces the statistical linearization method, whereas for bimodal systems, it still provides meaningful and accurate results with very low computational cost.

For the sake of simplicity, we will present our method through a specific system involving a nonlinear SDOF oscillator with a

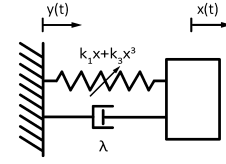


Fig. 1 Nonlinear energy harvester with normalized system parameters

double-well potential. This system has been studied extensively in the context of energy harvesting, especially in the case of white noise excitation (Daqaq, 2011; Daqaq, 2012; Gammaitoni et al., 2009; Ferrari et al., 2010). However, for realistic setups, it is important to be able to optimize/predict its statistical properties under general (colored) excitation. More specifically, we consider a nonlinear harvester of the form:

$$\ddot{x} + \lambda \dot{x} + k_1 x + k_3 x^3 = \ddot{y} \quad (1)$$

where x is the relative displacement between the harvester mass and the base, y is the base excitation representing a stationary stochastic process, λ is the normalized (with respect to mass) damping coefficient, and k_1 and k_3 are normalized stiffness coefficients (see Fig. 1).

Two-Time Moment System

We consider two generic time instants, t and s . We multiply the equation of motion at time t with the response displacement $x(s)$ and apply the mean value operator $\overline{\quad}$ (ensemble average). This will give us an equation that contains an unknown term on the right-hand side. To determine this term, we repeat the same steps but we multiply the equation of motion with $y(s)$. This gives us the following two-time moment equations:

$$\overline{\ddot{x}(t)y(s)} + \lambda \overline{\dot{x}(t)y(s)} + k_1 \overline{x(t)y(s)} + k_3 \overline{x(t)^3 y(s)} = \overline{\ddot{y}(t)y(s)} \quad (2)$$

$$\overline{\ddot{x}(t)x(s)} + \lambda \overline{\dot{x}(t)x(s)} + k_1 \overline{x(t)x(s)} + k_3 \overline{x(t)^3 x(s)} = \overline{\ddot{y}(t)x(s)} \quad (3)$$

Here the excitation is assumed to be a stationary stochastic process with zero mean and a given power spectral density; this can have an arbitrary form, e.g., monochromatic, colored, or white noise. Since the system is characterized by an odd restoring force, we expect that its response will also have zero mean. Moreover, we assume that after an initial transient phase, the system will be reaching a statistical steady state, given the stationary character of the excitation. Based on properties of mean square calculus (Sobczyk, 2001; Beran, 1994), we interchange the differentiation and the mean value operators. Then the moment equations will take the form:

$$\begin{aligned} \frac{\partial^2}{\partial t^2} \overline{x(t)y(s)} + \lambda \frac{\partial}{\partial t} \overline{x(t)y(s)} + k_1 \overline{x(t)y(s)} + k_3 \overline{x(t)^3 y(s)} \\ = \frac{\partial^2}{\partial t^2} \overline{y(t)y(s)} \end{aligned} \quad (4)$$

$$\begin{aligned} \frac{\partial^2}{\partial t^2} \overline{x(t)x(s)} + \lambda \frac{\partial}{\partial t} \overline{x(t)x(s)} + k_1 \overline{x(t)x(s)} + k_3 \overline{x(t)^3 x(s)} \\ = \frac{\partial^2}{\partial t^2} \overline{y(t)x(s)} \end{aligned} \quad (5)$$

Expressing everything in terms of the covariance functions will result in:

$$\frac{\partial^2}{\partial t^2} C_{xy}^{ts} + \lambda \frac{\partial}{\partial t} C_{xy}^{ts} + k_1 C_{xy}^{ts} + k_3 \overline{x(t)^3 y(s)} = \frac{\partial^2}{\partial t^2} C_{yy}^{ts} \quad (6)$$

$$\frac{\partial^2}{\partial t^2} C_{xx}^{ts} + \lambda \frac{\partial}{\partial t} C_{xx}^{ts} + k_1 C_{xx}^{ts} + k_3 \overline{x(t)^3 x(s)} = \frac{\partial^2}{\partial t^2} C_{yx}^{ts} \quad (7)$$

where the covariance function is defined as:

$$C_{xy}^{ts} = \overline{x(t)y(s)} = C_{xy}(t-s) = C_{xy}(\tau) \quad (8)$$

Taking into account the assumption for a stationary response (after the system has gone through an initial transient phase), we can rewrite the above moment equations in terms of the time difference $\tau = t - s$:

$$\begin{aligned} \frac{\partial^2}{\partial \tau^2} C_{xy}(\tau) + \lambda \frac{\partial}{\partial \tau} C_{xy}(\tau) + k_1 C_{xy}(\tau) + k_3 \overline{x(t)^3 y(s)} \\ = \frac{\partial^2}{\partial \tau^2} C_{yy}(\tau) \end{aligned} \quad (9)$$

$$\begin{aligned} \frac{\partial^2}{\partial \tau^2} C_{xx}(\tau) + \lambda \frac{\partial}{\partial \tau} C_{xx}(\tau) + k_1 C_{xx}(\tau) + k_3 \overline{x(t)^3 x(s)} \\ = \frac{\partial^2}{\partial \tau^2} C_{xy}(-\tau) \end{aligned} \quad (10)$$

The above procedure completes the derivation of the moment equations describing the dynamics of the system in a statistical steady state. Note that all the linear terms in the original system's equation are expressed in terms of the covariance functions, while the nonlinear (cubic) terms show up in the form of fourth-order moments. To compute the latter, we will need to adopt an appropriate closure scheme.

Two-Time PDF Representation and Induced Closure Schemes

In the absence of higher-than-two order moments, the response statistics can be analytically obtained in a straightforward manner. However, for higher-order terms, it is necessary to adopt an appropriate closure scheme that will close the infinite system of moment equations. A standard approach in this case, which performs very well for unimodal systems, is the application of Gaussian closure, which utilizes Isserlis' theorem (Isserlis, 1918) to connect the higher-order moments with the second-order statistical quantities. Despite its success for unimodal systems, Gaussian closure does not provide accurate results for bistable systems. This is because, in this case, the closure induced by the Gaussian assumption does not reflect the properties of the system attractor in the statistical steady state.

Here we aim to solve this problem by proposing a non-Gaussian representation for the joint response-response PDF at two different time instants and for the joint response-excitation PDF at two different time instants. These representations will:

- incorporate specific properties or information about the response PDF (single-time statistics) in the statistical steady state;
- incorporate a given correlation structure between the statistics of the response and the excitation, e.g., Gaussian;
- have a marginal PDF consistent with the excitation PDF (for the case of the joint response-excitation PDF); and
- induce a non-Gaussian closure scheme that will be consistent with all of the above properties.

Representation Properties for Single-Time Statistics

We begin by introducing the PDF properties for the single-time statistics. The selected representation will be based on the analytical solutions of the Fokker–Planck equation that are available for the case of white noise excitation (Soize, 1994; Sobczyk, 2001) and for vibrational systems that have an underlying Hamiltonian structure. Here we will leave the energy level of the system as a

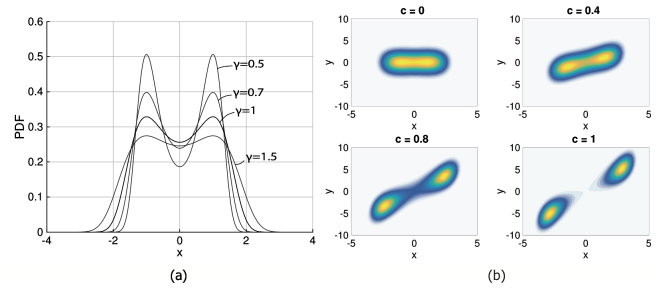


Fig. 2 (a) Representation of the steady-state PDF for single-time statistics of a system with double-well potential. The PDF is shown for different values of the system's energy level; (b) The joint-response excitation PDF is also shown for different values of the correlation parameter c ranging from small values (corresponding to large values of $|\tau|$) to larger ones (associated with smaller values of $|\tau|$).

free parameter (this will be determined later). In particular, we will consider the following family of PDF solutions (see Fig. 2a):

$$\begin{aligned} f(x; \gamma) &= \frac{1}{F} \exp\left\{-\frac{1}{\gamma} U(x)\right\} \\ &= \frac{1}{F} \exp\left\{-\frac{1}{\gamma} \left(\frac{1}{2} k_1 x^2 + \frac{1}{4} k_3 x^4\right)\right\} \end{aligned} \quad (11)$$

where U is the potential energy of the oscillator, γ is a free parameter connected with the energy level of the system, and F is the normalization constant expressed as:

$$F = \int_{-\infty}^{\infty} \exp\left\{-\frac{1}{\gamma} \left(\frac{1}{2} k_1 x^2 + \frac{1}{4} k_3 x^4\right)\right\} dx \quad (12)$$

Correlation Structure Between Two-Time Statistics

Representing the single-time statistics is not sufficient, since for correlated excitation, the system dynamics can be effectively expressed only through two-time (at least) statistics. Although the response steady-state PDF is assumed to have a non-Gaussian form, we represent the correlation between two different time instants having a Gaussian structure. Based on this assumption, we obtain PDF representations for the joint response-response and response-excitation at different time instants.

Joint Response-Excitation PDF. We first formulate the joint response-excitation PDF at two different time instants. Denoting with x the argument that corresponds to the response at time t , with y the argument for the excitation at time $s = t - \tau$, and with $g(y)$ the (zero-mean) marginal PDF for the excitation, we have the expression for the joint response-excitation PDF:

$$q(x, y) = \frac{1}{M} f(x) g(y) e^{cxy} \quad (13)$$

where M indicates a normalization constant and c defines the degree of correlation between the response and the excitation.

We note that the semipositive definite property of the covariance matrix associated with this process defines a range of possible values for the constant c . In particular, denoting with Σ the covariance matrix that describes the correlation at different time instants, we have:

$$\Sigma = \begin{bmatrix} \sigma_x^2 & \sigma_{xy} \\ \sigma_{xy} & \sigma_y^2 \end{bmatrix} \quad (14)$$

This matrix should be semipositive definite; i.e., for every nonzero column vector u , the following should be satisfied:

$$u^T \Sigma u \geq 0 \quad (15)$$

Since the above matrix has a positive trace, the semipositive definite property is guaranteed if and only if the determinant is greater than or equal to zero. This condition provides a relation between the covariance σ_{xy} (connected with c) and the variances of the marginal distributions:

$$-\sqrt{\sigma_x^2 \sigma_y^2} \leq \sigma_{xy} \leq \sqrt{\sigma_x^2 \sigma_y^2} \quad (16)$$

To connect the covariance σ_{xy} with c , we expand the former in a Taylor series, keeping up to the third-order terms in c :

$$\begin{aligned} \sigma_{xy} &= \frac{1}{M} \iint xyf(x)g(y)e^{cxy} dx dy \\ &= \overline{x^2 y^2} c + \frac{1}{6} \left\{ \overline{x^4 y^4} - 3(\overline{x^2})^2 (\overline{y^2})^2 \right\} c^3 \end{aligned} \quad (17)$$

This will give us the following condition for c :

$$-\sqrt{\overline{x^2 y^2}} \leq \overline{x^2 y^2} c + \frac{1}{6} \left\{ \overline{x^4 y^4} - 3(\overline{x^2})^2 (\overline{y^2})^2 \right\} c^3 \leq \sqrt{\overline{x^2 y^2}} \quad (18)$$

For the systems considered in this paper, we found that a third-order expansion is necessary and sufficient for good numerical results.

Joint Response-Response PDF. The joint PDF for two different time instants of the response, denoted as $p(x, z)$, is a special case of what has been presented previously. In order to avoid confusion, a different notation z is used to represent the response displacement at a different time instant s . Then we have:

$$p(x, z) = \frac{1}{N} f(x)f(z)e^{cxz} \quad (19)$$

where N is a normalization constant and c is a correlation constant. As stated previously, the correlation between two time instants has been assumed to have a Gaussian structure, and similar constraints on the possible values of c hold for this case as previously. We also note that the response displacement z at a different time instant still follows the same non-Gaussian PDF corresponding to the single-time statistics of the response (Eq. 11).

In Fig. 2b, we present the above joint PDF (Eq. 13) with the marginal f (response) having a bimodal structure and the marginal g (excitation) having a Gaussian structure. For $c = 0$, we have independence, which essentially expresses the case of very distant two-time statistics, while as we increase c , the correlation between the two variables increases, referring to the case of small values of τ .

Induced Non-Gaussian Closure

Using these non-Gaussian PDF representations, we will approximate the fourth-order moment terms that show up in the moment equations. In the context of the PDF representations given above, the relation between $\overline{x(t)^3 x(s)}$ and $\overline{x(t)x(s)}$ is very close to linear (see Fig. 3).

To this end, we choose a closure of the form (for both the response-response and the response-excitation terms):

$$\overline{x(t)^3 x(s)} = \rho_{x,x} \overline{x(t)x(s)} \quad (20)$$

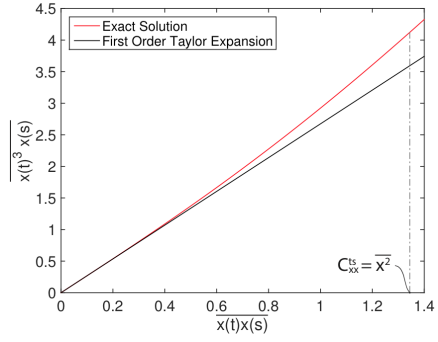


Fig. 3 The relation between $\overline{x(t)^3 x(s)}$ and $\overline{x(t)x(s)}$. The exact relation is illustrated by the red curve, and the approximated relation using non-Gaussian PDF representations is illustrated by the black curve.

where $\rho_{x,x}$ is the closure coefficient. The value of $\rho_{x,x}$ can be found if we expand both $\overline{x(t)^3 x(s)}$ and $\overline{x(t)x(s)}$ with respect to c . A first-order Taylor expansion will give:

$$\rho_{x,x} = \frac{\overline{x^4 x^2} c}{\overline{x^2 x^2} c} = \frac{\overline{x^4}}{\overline{x^2}} \quad (21)$$

Therefore, for a given marginal f , we can find analytically what would be the closure coefficient under the assumptions of the adopted closure scheme. Note that this constant depends directly on the energy level of the system defined by γ since the moments $\overline{x^2}$ and $\overline{x^4}$ depend on it. Similar relations can be derived for the term $\overline{x(t)^3 y(s)}$. We will refer to Eq. 21 as the ‘‘closure constraint.’’ This will be one of two constraints that we will include in the minimization procedure for the determination of the solution.

Closed Moment Equations

The next step involves the application of the closure scheme above on the derived two-time moment equations. By direct application of the induced closure schemes of Eq. 9 and Eq. 10, we have the linear set of moment equations for the second-order statistics:

$$\begin{aligned} \frac{\partial^2}{\partial \tau^2} C_{xy}(\tau) + \lambda \frac{\partial}{\partial \tau} C_{xy}(\tau) + (k_1 + \rho_{x,y} k_3) C_{xy}(\tau) \\ = \frac{\partial^2}{\partial \tau^2} C_{yy}(\tau) \end{aligned} \quad (22)$$

$$\begin{aligned} \frac{\partial^2}{\partial \tau^2} C_{xx}(\tau) + \lambda \frac{\partial}{\partial \tau} C_{xx}(\tau) + (k_1 + \rho_{x,x} k_3) C_{xx}(\tau) \\ = \frac{\partial^2}{\partial \tau^2} C_{xy}(-\tau) \end{aligned} \quad (23)$$

Using the Wiener–Khinchin theorem, we transform the above equations to the corresponding equations for the power spectral density:

$$\{(j\omega)^2 + \lambda(j\omega) + k_1 + \rho_{x,y} k_3\} S_{xy}(\omega) = (j\omega)^2 S_{yy}(\omega) \quad (24)$$

$$\{(j\omega)^2 - \lambda(j\omega) + k_1 + \rho_{x,x} k_3\} S_{xx}(\omega) = (j\omega)^2 S_{xy}(\omega) \quad (25)$$

These equations allow us to obtain an expression for the power spectral density of the response displacement in terms of the excitation spectrum:

$$\begin{aligned} S_{xx}(\omega) = \frac{\omega^4}{\left\{ k_1 + \rho_{x,y} k_3 - \omega^2 + j(\lambda\omega) \right\} \left\{ k_1 + \rho_{x,x} k_3 - \omega^2 - j(\lambda\omega) \right\}} \\ \times S_{yy}(\omega) \end{aligned} \quad (26)$$

Integrating the last equation will give us the variance of the response displacement:

$$\begin{aligned} \overline{x^2} &= \int_0^\infty S_{xx}(\omega) d\omega \\ &= \int_0^\infty \left| \frac{\omega^4}{\{k_1 + \rho_{x,y}k_3 - \omega^2 + j(\lambda\omega)\}\{k_1 + \rho_{x,x}k_3 - \omega^2 - j(\lambda\omega)\}} \right| \\ &\quad \times S_{yy}(\omega) d\omega \end{aligned} \quad (27)$$

Minimizing the deviation of the right-hand side from the left-hand side of the last equation is the second constraint, the dynamics constraint, which we will try to minimize together with the closure constraint defined by Eq. 21. It expresses the second-order dynamics of the system.

Moment Equation Closure Minimization (MECM) Method

The last step is the minimization of the two constraints, the closure constraint (Eq. 21) and the dynamics constraint (Eq. 27), which have been expressed in terms of the system response variance $\overline{x^2}$. The minimization will be done in terms of the unknown energy level γ and the closure coefficient $\rho_{x,x}$. More specifically, we define the following cost function, which incorporates the two constraints:

$$\begin{aligned} J(\gamma, \rho_{x,x}) &= \left(\overline{x^2} - \int_0^\infty \left| \frac{\omega^4 S_{yy}(\omega)}{\{k_1 + \rho_{x,y}k_3 - \omega^2 + j(\lambda\omega)\}\{k_1 + \rho_{x,x}k_3 - \omega^2 - j(\lambda\omega)\}} \right| d\omega \right)^2 \\ &\quad + \left(\overline{x^2} - \frac{\overline{x^4}}{\rho_{x,x}} \right)^2 \end{aligned} \quad (28)$$

Note that, in the context of statistical linearization, only the first constraint is minimized, while the closure coefficient is the one that follows exactly from a Gaussian representation. Therefore, in this context there is no attempt to incorporate in an equal way the effect of error in the dynamics and the error in the PDF representation. Minimization of this function essentially imposes interplay between these two factors in order to obtain a solution that satisfies both as closely as possible. For linear systems and an adopted Gaussian PDF for the response, as expected, the above cost function vanishes identically.

We also emphasize that in the above cost function, we have only included the closure coefficient $\rho_{x,x}$ for the joint PDF involving the response-response statistics. The corresponding coefficient for the joint response-excitation statistics $\rho_{x,y}$ is taken to be identical to the one obtained through the expansion of the moments as follows:

$$\rho_{x,y} = \frac{\overline{x^3 y}}{\overline{x y}} = \frac{\overline{x^4 y^2 c} + \frac{1}{6}(3\overline{x^6 (y^2)^2} - 3\overline{x^4 x^2 (y^2)^2})c^3}{\overline{x^2 y^2 c} + \frac{1}{6}(3\overline{x^4 (y^2)^2} - 3(\overline{x^2})^2(\overline{y^2})^2)c^3}, \quad c = c_r \quad (29)$$

where the moments have been expanded in a Taylor series (up to the third order) with respect to c as in Eq. 17, and c is taken to be equal to the maximum correlation parameter, c_r , which satisfies the condition in Eq. 18. We choose c in this way so that we have the best possible approximation of the closure coefficient when we are closer to the strongly correlated regime, i.e., for small values of $|\tau|$. With this choice the closure coefficient $\rho_{x,y}$ becomes a known function of the energy level γ and the excitation variance.

APPLICATION

We apply the described MECM method to a nonlinear vibrational system, which is an SDOF bistable oscillator with linear damping

that simulates energy harvesting. For the application, it is assumed that the stationary stochastic excitation has a power spectral density given by the Pierson–Moskowitz spectrum, which is typical for excitation created by random water waves:

$$S(\omega) = q \frac{1}{\omega^5} \exp\left(-\frac{1}{\omega^4}\right) \quad (30)$$

where q controls the intensity of the excitation.

SDOF Bistable Oscillator Excited by Colored Noise

For the colored noise excitation that we just described, we apply the MECM method. We consider a set of system parameters that correspond to a double-well potential. Depending on the intensity of the excitation (which is adjusted by the factor q), the response of the bistable system “lives” in three possible regimes. If q is very low, the bistable system is trapped in either of the two wells, while if q is very high, the energy level is above the homoclinic orbit and the system performs cross-well oscillations. Between these two extreme regimes, the stochastic response exhibits combined features and characteristics of both energy levels, and it has a highly nonlinear, multifrequency character (Dykman et al., 1985; Dykman et al., 1988).

Despite these challenges, the presented MECM method can inexpensively provide a very good approximation of the system’s statistical characteristics, as shown in Fig. 4. In particular in Fig. 4, we present the response variance as the intensity of the excitation varies for two cases of the system’s parameters. We also compare our results with direct Monte Carlo simulations and with a standard Gaussian closure method (Sobczyk, 2001; Soong and Grigoriu, 1993; Grigoriu, 2002). For the application of the MECM method, we employ the PDF representation (Eq. 11).

We observe that for very large values of q , the computed approximation closely follows the Monte Carlo simulation. On the other hand, the Gaussian closure method systematically underestimates the variance of the response. For lower intensities of the excitation, the exact (Monte Carlo) variance presents a nonmonotonic behavior with respect to q due to the coexistence of the cross-well and intrawell oscillations. Although the Gaussian closure has very poor performance on capturing this trend, the MECM method can still provide a satisfactory approximation of the dynamics. Note that the nonsmooth transition observed in the MECM curve is due to the fact that for very low values of q , the minimization of the cost function (Eq. 28) does not reach a zero value, although this is the case for higher values of q . In other words, in the strongly nonlinear regime, neither the dynamics constraint nor the closure constraint is satisfied exactly, yet this optimal solution provides a good approximation of the system dynamics.

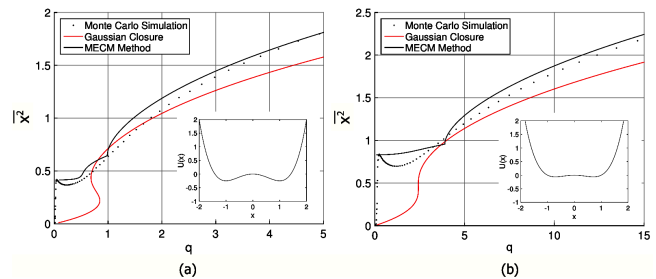


Fig. 4 Mean square displacement with respect to the amplification factor of the Pierson–Moskowitz spectrum for a bistable system with two different system parameters: (a) $\lambda = 1$, $k_1 = -1$, and $k_3 = 1$; (b) $\lambda = 0.5$, $k_1 = -0.5$, and $k_3 = 1$

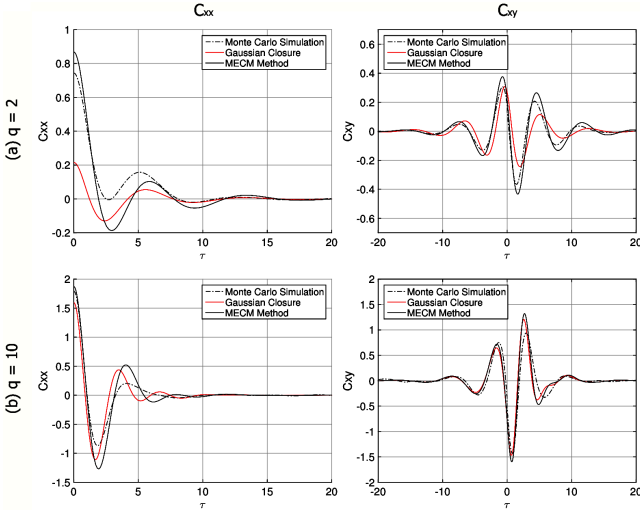


Fig. 5 Correlation functions C_{xx} and C_{xy} of the bistable system with system parameters $\lambda = 1$, $k_1 = -1$, and $k_3 = 1$ subjected to the Pierson–Moskowitz spectrum: (a) Amplification factor of $q = 2$; (b) Amplification factor of $q = 10$

After we have obtained the unknown parameters γ and $\rho_{x,x}$ by minimizing the cost function for each given q , we can then compute, in a postprocess manner, the covariance functions and the joint PDF. More specifically, since a known γ allows for a given $\rho_{x,y}$ (Eq. 29), we can immediately determine $C_{xy}(\tau)$ by taking the inverse Fourier transform of S_{xy} found through Eq. 24. The next step is the numerical integration of the closed moment Eq. 23 utilizing the determined value $\rho_{x,x}$ with initial conditions given by:

$$C_{xx}(0) = \int x^2 f(x; \gamma) dx \quad \text{and} \quad \dot{C}_{xx}(0) = 0 \quad (31)$$

where the second condition follows from the symmetry properties of C_{xx} . Note that we integrate Eq. 23 instead of using the inverse Fourier transform as we did for $C_{xy}(\tau)$ so that we can impose the variance found by integrating the resulting density for the determined γ . The results, as well as a comparison with the Gaussian closure method and a direct Monte Carlo simulation, are presented in Fig. 5. We can observe that through the proposed approach, we are able to satisfactorily approximate the correlation function, even close to the nonlinear regime $q = 2$, where the Gaussian closure method presents important discrepancies.

Finally, using the computed parameters γ and $\rho_{x,x}$, we can also approximate the non-Gaussian joint PDF for the response-response excitation at different time instants. This will be given by:

$$f_{x(t)x(t+\tau)y(t)}(x, z, y) = \frac{1}{R} f(x; \gamma) f(z; \gamma) g(y) \exp(c_1 xz + c_2 yz + c_3 xy) \quad (32)$$

where R is a normalization constant and the parameters c_1 , c_2 , c_3 are found by expanding the corresponding moments in a Taylor expansion, i.e., through the approximations:

$$C_{xx}(\tau) = \iiint xz f_{x(t)x(t+\tau)y(t)}(x, z, y) dx dy dz = c_1 (\bar{x}^2)^2 + O(c_1^2) \quad (33)$$

$$C_{xy}(\tau) = \iiint yz f_{x(t)x(t+\tau)y(t)}(x, z, y) dx dy dz = c_2 \bar{x}^2 \bar{y}^2 + O(c_2^2) \quad (34)$$

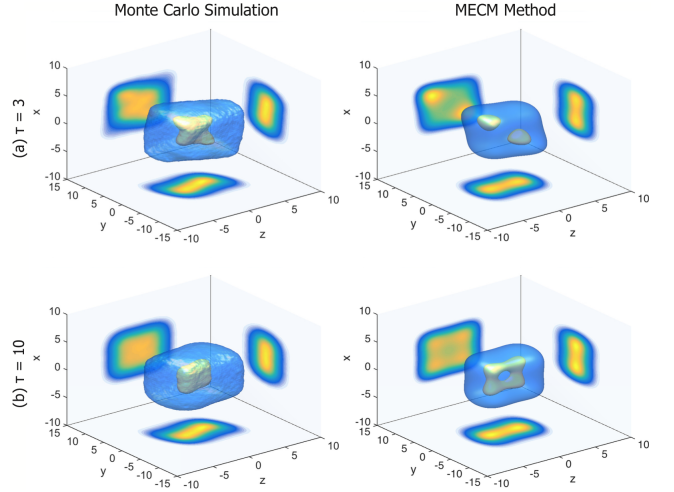


Fig. 6 Joint PDF $f_{x(t)x(t+\tau)y(t)}(x, z, y)$ computed using the MECM method and direct Monte Carlo simulations. The system parameters are given by $\lambda = 1$, $k_1 = -1$, and $k_3 = 0.3$, and the excitation is Gaussian following a Pierson–Moskowitz spectrum with $q = 20$. The PDF is presented through two-dimensional marginal PDFs as well as through isosurfaces: (a) $\tau = 3$; (b) $\tau = 10$.

$$C_{xy}(0) = \iiint xy f_{x(t)x(t+\tau)y(t)}(x, z, y) dx dy dz = c_3 \bar{x}^2 \bar{y}^2 + O(c_3^2) \quad (35)$$

If necessary, higher-order terms may be retained in the Taylor expansion, although for the present problem, a linear approximation was sufficient. The computed approximation is presented in Fig. 6 through two-dimensional marginal PDFs as well as through isosurfaces of the full three-dimensional joint PDF. We compare with direct Monte Carlo simulations, and as we are able to observe, the computed PDF closely approximates the expensive Monte Carlo simulation. We emphasize that in order to accurately capture the joint statistics using the Monte Carlo approach, we had to use 10^7 number of samples. On the other hand, the computational cost through the MECM method is trivial.

CONCLUSIONS

We have considered the problem of determining the non-Gaussian steady-state statistical structure of bistable nonlinear vibrational systems subjected to colored noise excitation. We first derived moment equations that describe the dynamics governing the two-time statistics. We then combined those with a non-Gaussian PDF representation for the joint response-excitation statistics. This representation has: (i) a single-time statistical structure consistent with the analytical solutions of the Fokker–Planck equation and (ii) a two-time statistical structure with Gaussian characteristics. Using this PDF representation, we derived a closure scheme that we formulated in terms of a consistency condition involving the second-order statistics of the response, the closure constraint. A similar condition, the dynamics constraint, was derived directly through moment equations. We then formulated the two constraints as a low-dimensional minimization problem with respect to the unknown parameters of the representation. The minimization of both the dynamics constraint and the closure constraint imposes interplay between these two factors in order to obtain a solution that satisfies both constraints as closely as possible.

We then applied the presented method to a nonlinear oscillator in the context of ocean wave energy harvesting, which is a single

degree of freedom (SDOF) bistable oscillator with linear damping. For the application, it was assumed that the stationary stochastic excitation has a power spectral density given by the Pierson–Moskowitz spectrum. We have shown that the presented method can provide a very good approximation of the system’s second-order statistics when compared with direct Monte Carlo simulations, even in essentially nonlinear regimes, where Gaussian closure techniques fail completely to capture the dynamics. In addition, we can compute, in a postprocess manner, the full (non-Gaussian) probabilistic structure of the solution. We emphasize that the computational cost associated with the new method is considerably smaller than that associated with methods that evolve the PDF of the solution, since it relies on the minimization of a function with a few unknown variables.

These results indicate that the new method can be a very good candidate when it comes to the calculation of the stochastic response for a vibrational system with complex potentials, as it is required in parameter optimization or selection. Future endeavors include the application of the presented approach in higher-dimensional contexts involving nonlinear energy harvesters and passive protection of structures, as well as in the development/optimization of structural configurations able to operate effectively under intermittent loads (Mohamad and Sapsis, 2015).

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